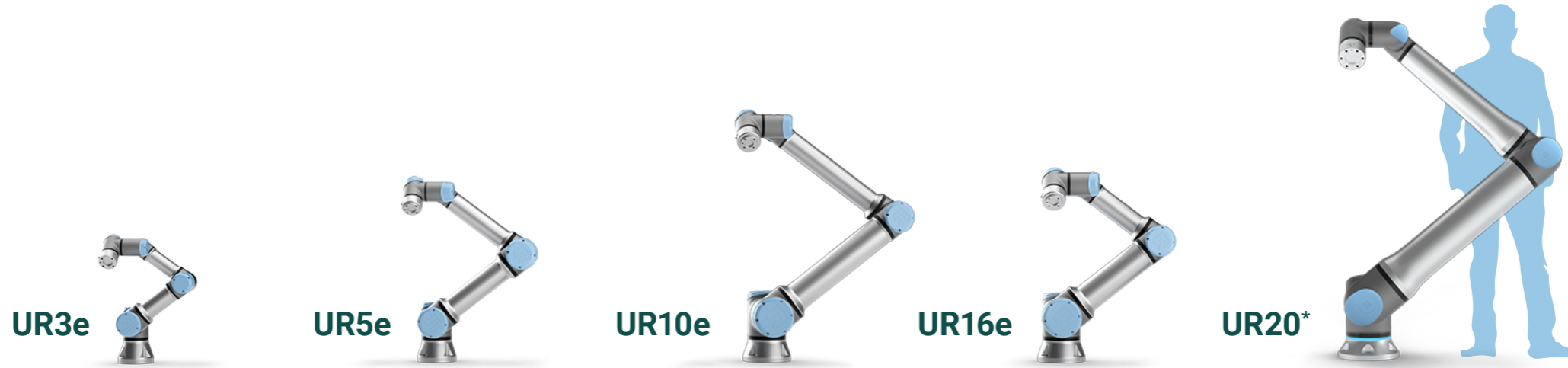


Robot arm

Technical specification



Specification

Payload at full CoG offset and in the entire workspace	3 kg (6.6 lbs)	5 kg (11 lbs)	12.5 kg (27.5 lbs)	16 kg (35.3 lbs)	20 kg (44.1 lbs)
Reach	500 mm (19.7 in)	850 mm (33.5 in)	1300 mm (51.2 in)	900 mm (35.4 in)	1750 mm (68.9 in)
Degrees of freedom	< 6 rotating joints >			< 6 rotating joints >	
Programming	< 12 inch touchscreen with PolyScope graphical user interface >			< 12 inch touchscreen with PolyScope graphical user interface >	

Performance

Power consumption					
Maximum power	300 W	570 W	615 W	585 W	750 W
Moderate operating settings	100 W	200 W	350 W	350 W	500 W
Safety	< 17 configurable safety functions >			< 17 configurable safety functions >	
Certifications	< EN ISO 13849-1, PLd category 3, EN ISO 10218-1 >			< EN ISO 13849-1, PLd category 3, EN ISO 10218-1 >	

Force sensing, tool flange	Force, x-y-z	Torque, x-y-z	Force, x-y-z	Torque, x-y-z	Force, x-y-z	Torque, x-y-z	Force, x-y-z	Torque, x-y-z	Force, x-y-z	Torque, x-y-z
Range	30.0 N	10.0 Nm	50.0 N	10.0 Nm	100.0 N	10.0 Nm	160.0 N	10.0 Nm	200 N	20.0 Nm
Precision	2.0 N	0.1 Nm	3.5 N	0.2 Nm	5.0 N	0.2 Nm	5.0 N	0.2 Nm	5.5 N	0.2 Nm
Accuracy	3.5 N	0.1 Nm	4.0 N	0.3 Nm	5.5 N	0.5 Nm	5.5 N	0.5 Nm	10 N	1 Nm

Movement

Pose repeatability per ISO 9283	± 0.03 mm		± 0.03 mm		± 0.05 mm		± 0.05 mm		± 0.05 mm	
Axis Movement	Working range	Maximum speed	Working range	Maximum speed	Working range	Maximum speed	Working range	Maximum speed	Working range	Maximum speed
Base	± 360°	± 180°/s	± 360°	± 180°/s	± 360°	± 120°/s	± 360°	± 120°/s	± 360°	± 120°/s
Shoulder	± 360°	± 180°/s	± 360°	± 180°/s	± 360°	± 120°/s	± 360°	± 120°/s	± 360°	± 120°/s
Elbow	± 360°	± 180°/s	± 360°	± 180°/s	± 360°	± 180°/s	± 360°	± 180°/s	± 360°	± 150°/s
Wrist 1	± 360°	± 360°/s	± 360°	± 180°/s	± 360°	± 180°/s	± 360°	± 180°/s	± 360°	± 210°/s
Wrist 2	± 360°	± 360°/s	± 360°	± 180°/s	± 360°	± 180°/s	± 360°	± 180°/s	± 360°	± 210°/s
Wrist 3	Infinite	± 360°/s	± 360°	± 180°/s	± 360°	± 180°/s	± 360°	± 180°/s	± 360°	± 210°/s

Features

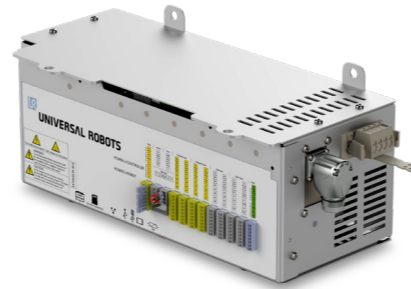
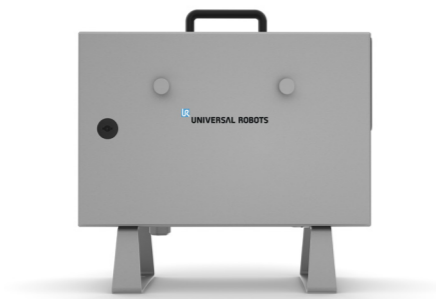
IP classification	IP54	IP54	IP54	IP54	IP54
ISO 14644-1 class cleanroom	5	5	5	5	5
Noise	> 60 dB(A)	> 65 dB(A)	> 65 dB(A)	> 65 dB(A)	> 65 dB(A)
Robot mounting	Any Orientation	Any Orientation	Any Orientation	Any Orientation	Any Orientation
I/O Ports					
Digital in	2	2	2	2	2
Digital out	2	2	2	2	2
Analog in	2	2	2	2	2
Tool I/O power supply voltage	12/24 V	12/24 V	12/24 V	12/24 V	12/24 V
Tool I/O power supply	600 mA	1.5 A (Dual pin) 1 A (Single pin)	2 A (Dual pin) 1 A (Single pin)	2 A (Dual pin) 1 A (Single pin)	2 A (Dual pin) 1 A (Single pin)

Physical

Footprint	Ø 128 mm	Ø 149 mm	Ø 190 mm	Ø 190mm	Ø 245 mm
Materials	< Aluminium, Plastic, Steel >			< Aluminium, Plastic, Steel >	
Tool flange connector type	< M8 M8 8-pin (male), EN ISO-9409-1-50-4-M6 >			< M8 M8 8-pin (male), EN ISO-9409-1-50-4-M6 >	
Cable length (robot arm)	< 6 m (236 in) >			< 6 m (236 in) >	
Weight including cable	11.2 kg (24.7 lbs)	20.6 kg (45.4 lbs)	33.5 kg (73.9 lbs)	33.1 kg (73 lbs)	64 kg (141.1 lbs)
Operating temperature range	< 0-50 °C (32-122 °F) >			< 0-50 °C (32-122 °F) >	
Humidity	< 90%RH (non-condensing) >			< 90%RH (non-condensing) >	

Control box and teach pendant

Technical specification



Control box	CB 5.2	CB 5.5*	OEM 5.2	OEM 5.5*
Features				
Robot types	UR3e, UR5e, UR10e, UR16e	UR3e, UR5e, UR10e, UR16e, UR20	UR3e, UR5e, UR10e, UR16e	UR3e, UR5e, UR10e, UR16e, UR20
Software compatibility	PolyScope 5 and below	All PolyScope versions	PolyScope 5 and below	All PolyScope versions
IP classification	IP44	IP44	IP20	IP20
ISO 14644-1 class cleanroom	6	6	6	6
Operating temperature range	0-50 °C (32-122 °F)	0-50 °C (32-122 °F)	0-50 °C (32-122 °F)	0-50 °C (32-122 °F)
I/O Ports				
Digital In	16	16	16	16
Digital Out	16	16	16	16
Analog In	2	2	2	2
Analog Out	2	2	2	2
Quadrature Digital Inputs	4	4	4	4
I/O power supply	24V, 2A	24V, 2A	24V, 2A	24V, 2A
Communication	Modbus TCP PROFINET Ethernet/IP USB 2.0, USB 3.0	Modbus TCP PROFINET Ethernet/IP USB 2.0, USB 3.0	Modbus TCP PROFINET Ethernet/IP USB 2.0, USB 3.0	Modbus TCP PROFINET Ethernet/IP USB 2.0, USB 3.0
RAM	2 GB	4 GB	2 GB	4 GB
Power Source	100-240 VAC, 47-440 Hz	100-240 VAC, 47-440 Hz	AC model: 100-240 VAC, 47-440 Hz DC model: 24 - 48 VDC	AC model: 100-240 VAC, 47-440 Hz DC model: 24 - 48 VDC

Physical				
Control box size (W x H x D)	460 mm x 449 mm x 254 mm (18.2 in x 17.6 in x 10 in)	460 mm x 449 mm x 254 mm (18.2 in x 17.6 in x 10 in)	451 mm x 168 mm x 150 mm (17.6 in x 6.6 in x 5.9 in)	451 mm x 168 mm x 150 mm (17.6 in x 6.6 in x 5.9 in)
Weight	12 kg (26.5 lbs)	12 kg (26.5 lbs)	AC model: 4.7 kg (10.4 lbs) DC model: 4.3 kg (9.5 lbs)	AC model: 4.7 kg (10.4 lbs) DC model: 4.3 kg (9.5 lbs)
Power supply output	UR3e: 600 W UR5e, UR10e, UR16e: 1500 W	UR3e: 600 W UR5e, UR10e, UR16e, UR20: 1500 W	UR3e: 600 W UR5e, UR10e, UR16e: 1500 W	UR3e: 600 W UR5e, UR10e, UR16e, UR20: 1500 W
Materials	Powdered coated steel	Powdered coated steel	Aluminium	Aluminium
Humidity	90 %RH (non-condensing)	90 %RH (non-condensing)	90 %RH (non-condensing)	90 %RH (non-condensing)

Teach pendant	Standard	3PE
Features		
Robot types	e-Series (standard)	e-Series (optional), UR20 (standard)
IP classification	IP54	IP54
Incl. in certifications	EN ISO 10218-1 EN ISO 13849-1	EN ISO 10218-1 EN ISO 13849-1
Humidity	90 %RH (non-condensing)	90 %RH (non-condensing)
Display resolution	1280 x 800 pixels	1280 x 800 pixels
Freedrive	1 button	2 buttons to support for right and left handed operation
Physical		
Materials	Plastic (PC/ASA)	Plastic (PC/ASA)
Teach pendant size	300 mm x 231 mm x 50 mm (11.8 in x 9.1 in x 1.97 in)	300 mm x 231 mm x 50 mm (11.8 in x 9.1 in x 1.97 in)
Weight (including 1 m TP cable)	1.6 kg (3.5 lbs)	1.8 kg (3.961 lbs)
Cable length (Teach pendant)	4.5 m (177.17 in)	4.5 m (177.17 in)